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Tech Paper

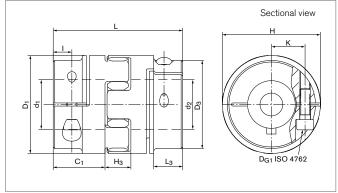
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Elastomer Jaw Couplings

RINGFEDER® GWE 5104

Servo-Insert coupling with clamping hubs and dual slits





	d ₁ ;d ₂	d _{1k} ;d _{2k}										
Size	min-max	min-max	C ₁	D ₁	D ₃	н	H ₃	ı	K	L	L ₃	
	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	
14	5 - 16	5 - 16	11	30	30	32,2	13	5	11	35		
19	6 - 20	6 - 20	25	40	40	46	16	12	14,5	66		
24	10 - 32	10 - 32	30	55	55	57	18	10,5	20	78		
28	10 - 38	10 - 38	35	65	65	71	20	11,5	24,5	90		
38	12 - 48	12 - 48	45	80	80	83	24	15,5	30	114		
42	14 - 54	14 - 54	50	95	85	95	26	18	32,5	126	28	
48	15 - 60	15 - 60	56	105	95	106	28	21	37	140	32	
55	35 - 74	35 - 74	65	120	120	120	30	26	45	160		
65	35 - 80	35 - 80	75	135	135	135	35	28	50	185		
75	30 - 95	30 - 95	85	160	160	160	40	36	60	210		

Transmission of the couplings transmissible torque T can not longer be guaranteed for certain with borings $< d_{min}$. Types with borings $< d_{min}$, however, can be supplied.

Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

Size	т	H _{es}	n _{max}	J	Gw	D _{G1}	T _{A1}
	Nm		1/min	10 ⁻³ kgm ²	kg	mm	Nm
14	12,5	98 SH A	13000	0,006	0,042	1 x M3	2
19	17	98 SH A	10000	0,036	0,158	1 x M6	11
24	60	98 SH A	7000	0,15	0,304	1 x M6	15
28	160	98 SH A	6000	0,33	0,505	1 x M8	32
38	325	98 SH A	5000	0,96	0,934	1 x M8	38
42	450	98 SH A	4000	4,92	3,8	1 x M10	84
48	525	98 SH A	3600	8,26	4,9	1 x M12	145
55	685	98 SH A	3150	19,15	10,2	1 x M12	145
65	940	98 SH A	2800	30,72	13,7	1 x M12	145
75	1920	98 SH A	2350	66,68	21,34	1 x M16	295

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Transmissible torque T [Nm]

	Transmissible torque																				
Size	Ø5	Ø6	Ø8	Ø10	Ø12	Ø14	Ø16	Ø20	Ø25	Ø30	Ø35	Ø40	Ø45	Ø50	Ø55	Ø60	Ø65	Ø70	Ø80	Ø90	Ø95
	Nm																				
14	4,8	6,0	7,7	9,4	11	12,5	12,5														
19		16	17	17	17	17	17	17													
24				37	43	50	56	60	60	60											
28				61	72	83	94	114	138	160	160										
38					87	100	113	138	168	197	225	251	277								
42						174	197	242	296	348	398	450	450								
48							276	343	424	502	525	525	525	525	525						
55											630	685	685	685	685	685	685	685			
65											634	714	791	866	940	940	940	940	940		
75											998	1125	1250	1370	1489	1604	1718	1830	1920	1920	1920

Explanations

 $d_1;d_{2min}$ = Min. bore diameter d₁/d₂

= Max. bore diameter d₁/d₂ d₁;d_{2max}

 $\mathbf{d_{1k}}; \mathbf{d_{2kmin}} = \text{Min. bore diameter } d_1/d_2$

with keyway acc. to DIN 6885-1

 $\mathbf{d_{1k}}; \mathbf{d_{2kmax}} = \text{Max. bore diameter } d_1/d_2$ with keyway acc. to DIN 6885-1

= Guided length in hub bore

 C_{1}

 D_1 = Outer diameter D₃ = Outer diameter hub

= Clearance diameter

= Length of damping module

= Distance between center screw hole and

= Distance shaft axis - clamping screw axis

L = Total length

= Length

= Transmissible torque at given T_A

= Hardness of the elastomeric spider

n_{max} = Max. rotation speed

= Total moment of inertia

Gw = Weight

D_{G1} = Thread

 T_{A1} = Tightened torque of clamping screw D_{G1}

Ordering example

Series Size	Bore diameter d ₁	Bore diameter d ₂	Spider hardness (optional) ¹⁾	Spider bore d _{bz} (optional) ¹⁾	Further details		
GWE 5104-42	40	41	64 SH D	42	*		

¹⁾ If a different spider hardness is selected, the detailed technical data for the sprockets must be observed. See chapter "Elastomer Jaw Couplings RINGFEDER® GWE Technical description" in Product Paper & Tech Paper "RINGFEDER® Elastomer Jaw Couplings"

Further information on

RINGFEDER® GWE 5104 on www.ringfeder.com

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^{*} Keyway